OmniGeo: Interactive Vision Language Models for Multi-Granularity, Multi-Sensor and Multi-Scale Earth Observation

Yan Shu, Paolo Rota, Nicu Sebe
University of Trento

Introduction

	visual prompt (region, point)		image-level (RGB,SAR)		Pixel-level (RGB, SAR)	
GeoChat	×	×	√	×	×	×
EarthGPT	×	×	√	√	×	×
Skyeye-GPT	×	×	√	×	×	×
EarthMarker	√	√	√	×	×	×
EarthDial	×	×	√	√	×	×
RsUniVLM	×	×	√	×	√	×
Geopixel	×	×	√	×	√	×
OmniGeo (Ours)	√	√	√	√	√	√

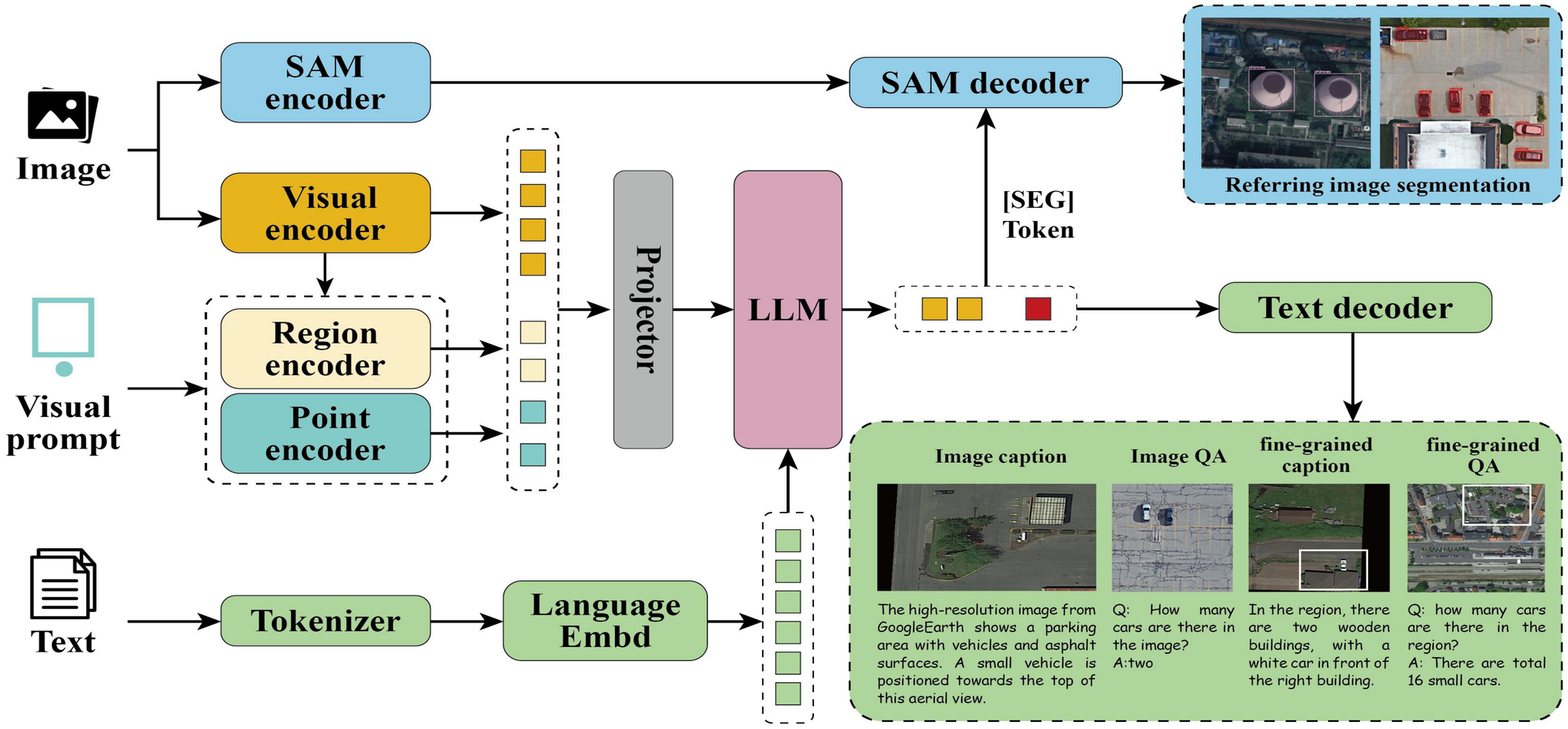
Motivation

- Existing Vision Languge Models (VLMs) has limited capacity in understanding and reasoning in RS domain
- **Interactive**: Accept different visual prompts to achive better interaction
- **Multi-Granularity**: Understand RS data from image-level to pixel-level
- **Multi-Sensor**: Understand RS data from differnet sensor (RGB and SAR)
- **Multi-Scale**: Understand RS data from different scales (drones or satellite)

Goals

- Proposing a MLLMs towards multi-granularity, mutli-sensor and multi-scale earth observation with flexible visual prompts.
- Proposing a compostite pretraining stage for better knowledge transfer from full-supervised natural image data to unsupervised RS data.
- Proposing a multi-task vision-language SAR data and benchmark.

Method



Experiment

Segmentation	RRSISD		RefSegrs	
	miou	oiou	miou	oiou
RRSIS (TGRS 2024)	-	-	60.0	76.8
RM-SIN (CVPR 2024)	64.2	77.8	-	-
CRO-BIM (Arxiv 2024.10)	64.5	76.0	59.7	72.3
OmniGeo (Ours)	**79.7**	**97.4**	**62.3**	**89.6**

Region caption task	METEOR	ROUGE	CIDEr	SPICE
GeoChat (CVPR 2024)	12.94	26.98	30.92	24.97
EarthGPT (TGRS 2024)	24.09	47.87	232.79	38.29
EarthMarker (TGRS 2024)	31.97	60.46	379.25	59.87
OmniGeo (Ours)	**36.55**	**68.53**	**491.20**	**67.62**

Future works

- **Benchmark construction, including perception and resaoning evaluation for mutli-sensor RS data.**
- **Composite pretraining stage ablation study.**
- **Extending to multi-spectrum and high-spectrum data.**